

Simplicial and Cellular Spanning Trees

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Graphs

A **graph** is a pair $G = (V, E)$, where

- ▶ V is a set of **vertices**, and
- ▶ E is a set of **edges**, each joining two vertices (its **endpoints**).

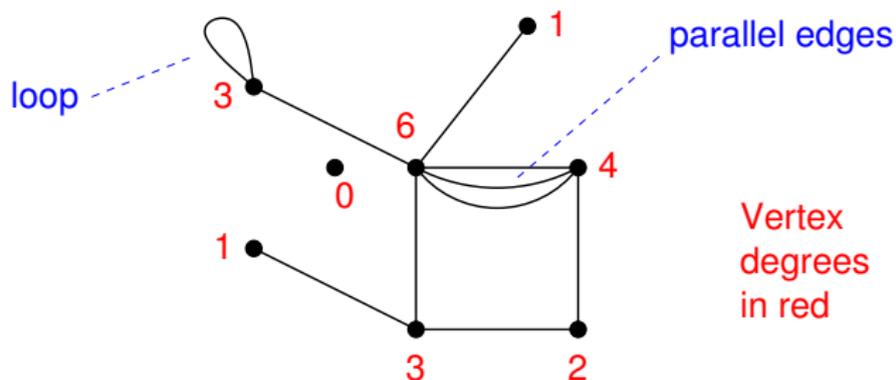
The **degree** of a vertex is the number of edges incident to it.

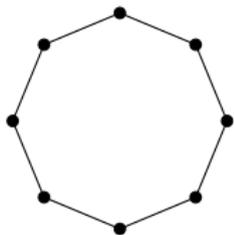
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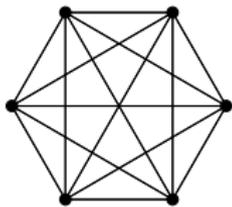
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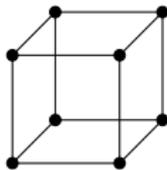




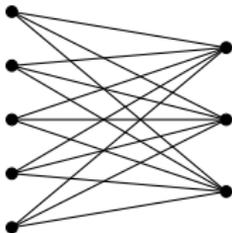
Cycle graph C_8



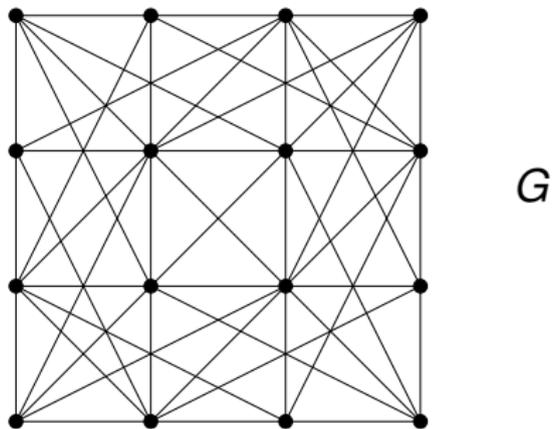
Complete graph K_6

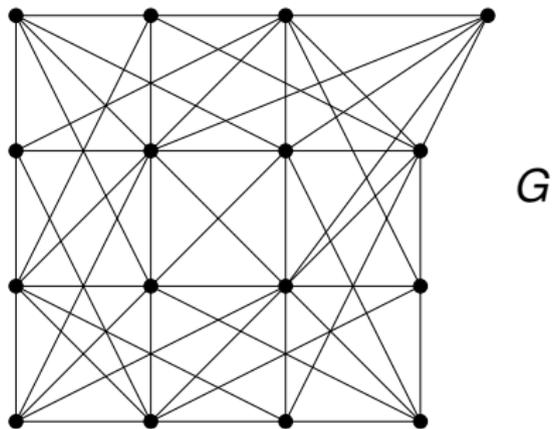


Cube graph Q_3



Complete bipartite graph $K_{5,3}$



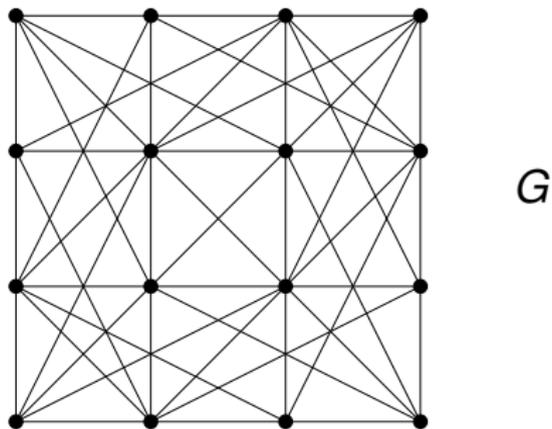


Definition A **spanning tree** of a graph G is a set of edges T (or a subgraph (V, T)) such that:

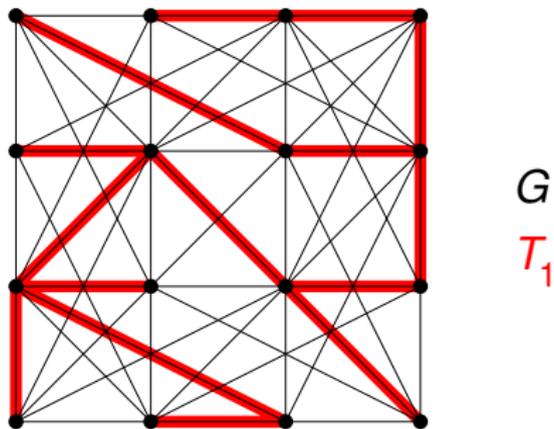
1. (V, T) is **connected**: every pair of vertices is joined by a path
2. (V, T) is **acyclic**: there are no cycles
3. $|T| = |V| - 1$.

Any two of these conditions together imply the third.

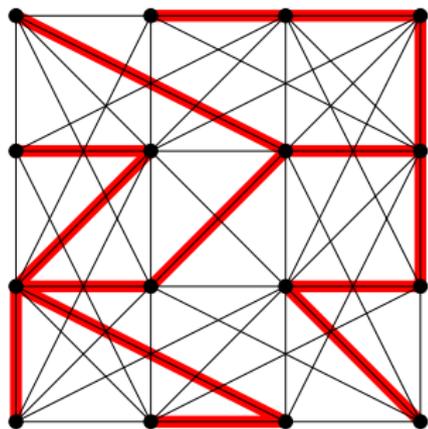
Spanning Trees



Spanning Trees



Spanning Trees



G

T_2

Counting Spanning Trees

$\mathcal{T}(G)$ = set of spanning trees of G

$\tau(G)$ = number of spanning trees of G

- ▶ $\tau(\text{tree}) = 1$
- ▶ $\tau(C_n) = n$
- ▶ $\tau(K_n) = n^{n-2}$ (Cayley's formula; highly nontrivial!)
- ▶ $\tau(K_{m,n}) = n^{m-1} m^{n-1}$
- ▶ Many other enumeration formulas for nice graphs

Deletion and Contraction

Let $e \in E(G)$.

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- ▶ **Deletion** $G - e$: Remove e

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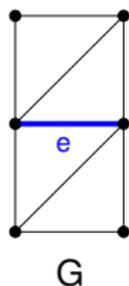
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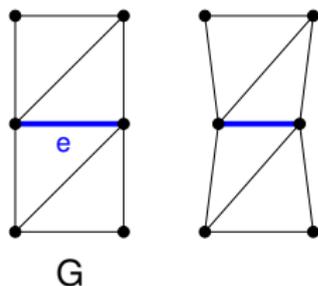
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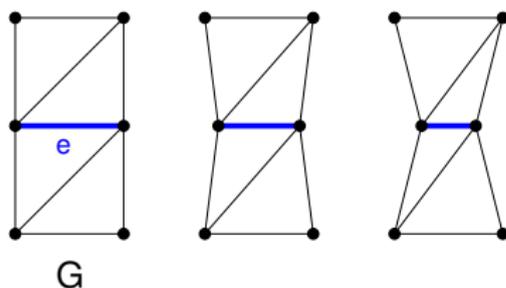
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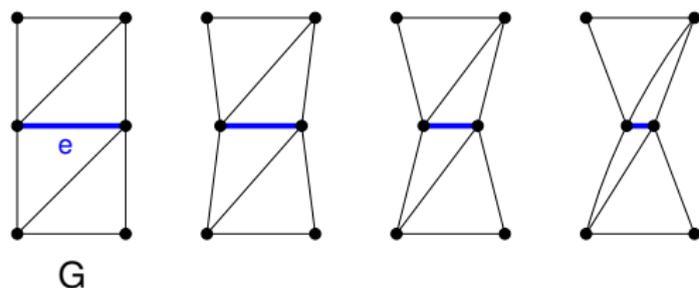
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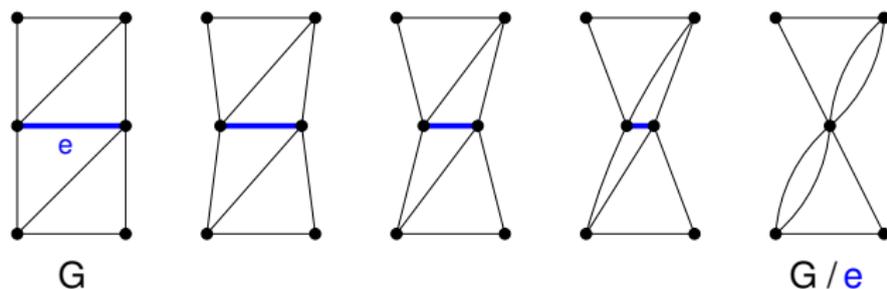
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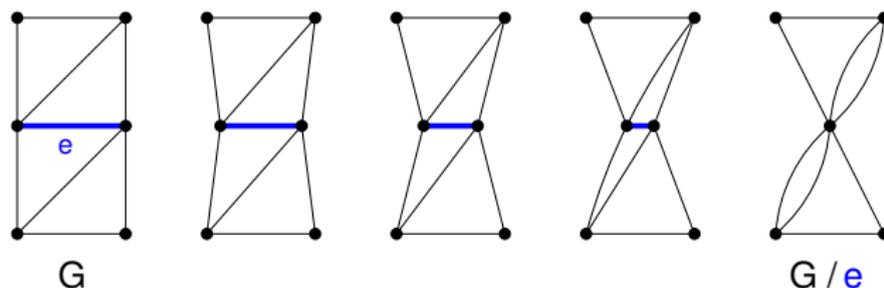
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Theorem $\tau(G) = \tau(G - e) + \tau(G/e)$.

Deletion and Contraction

Theorem $\tau(G) = \tau(G - e) + \tau(G/e)$.

This formula allows easy calculation of $\tau(G)$ and some fun results:

G							
$\tau(G)$	1	1	2	3	5	8	13

Unfortunately:

- ▶ “easy” does not mean “efficient”: $2^{|E|}$ steps are required to calculate $\tau(G)$ this way.
- ▶ Useful only for graph families with recursive deletion/contraction structure (*not* K_n , $K_{m,n}$, Q_n , etc.).

The Matrix-Tree Theorem

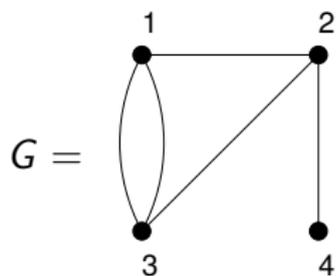
Definition Let G be a connected graph with vertices $[n] = \{1, \dots, n\}$ and no loops. The **Laplacian** of G is the $n \times n$ matrix $L = [\ell_{ij}]$:

$$\ell_{ij} = \begin{cases} \deg_G(i) & \text{if } i = j, \\ -(\text{number of edges from } i \text{ to } j) & \text{if } i \neq j. \end{cases}$$

- ▶ L is symmetric and positive semi-definite
 - ▶ $L = \partial\partial^T$, where $\partial =$ signed vertex-edge incidence matrix
- ▶ $\text{rank } L = n - 1$
- ▶ $\ker L$ is spanned by the all-1's vector

The Matrix-Tree Theorem

Example



$$L = \begin{bmatrix} 3 & -1 & -2 & 0 \\ -1 & 3 & -1 & -1 \\ -2 & -1 & 3 & 0 \\ 0 & -1 & 0 & 1 \end{bmatrix}$$

The Matrix-Tree Theorem

The Matrix-Tree Theorem (Kirchhoff, 1847)

(1) Let $0, \lambda_1, \lambda_2, \dots, \lambda_{n-1}$ be the eigenvalues of L . Then the number of spanning trees of G is

$$\tau(G) = \frac{\lambda_1 \lambda_2 \cdots \lambda_{n-1}}{n} .$$

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(2) Let $1 \leq i \leq n$. Form the **reduced Laplacian** L_i by deleting the i^{th} row and i^{th} column of L . Then

$$\tau(G) = \det L_i .$$

The Matrix-Tree Theorem: Proof Sketches

Proof Sketch #1: Use linear algebra and deletion/contraction.

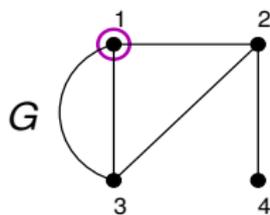
Proof Sketch #2: (Dall–Pfeifle 2014) Dissect one polyhedron with volume $\det L_i$ and reassemble it into one with volume $\tau(G)$. (Ask Ken for details.)

Proof Sketch #3: Let ∂ be the signed vertex/edge incidence matrix of G (so $\text{rank } \partial = n - 1$).

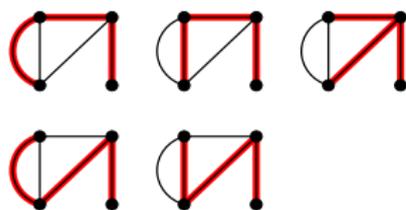
- ▶ Note that $L = \partial\partial^T$ and $L_i = \partial_i \partial_i^T$.
- ▶ Column bases of $\partial =$ spanning trees of G .
- ▶ Binet-Cauchy:

$$\det(\partial_i \partial_i^T) = \sum_{\substack{A \subseteq E(T) \\ |A|=n-1}} (\det \partial_A)^2 = \sum_{T \in \mathcal{T}(G)} (\pm 1)^2 = \tau(G).$$

The Matrix-Tree Theorem: Example



$$\tau(G) = 5$$



$$\partial = \begin{bmatrix} 1 & 1 & -1 & 0 & 0 \\ -1 & 0 & 0 & 1 & -1 \\ 0 & -1 & 1 & -1 & 0 \\ 0 & 0 & 0 & 0 & 1 \end{bmatrix}$$

$$L = \begin{bmatrix} 3 & -1 & -2 & 0 \\ -1 & 3 & -1 & -1 \\ -2 & -1 & 3 & 0 \\ 0 & -1 & 0 & 1 \end{bmatrix}$$

Eigenvalues: 0, 1, 4, 5

Hypercubes

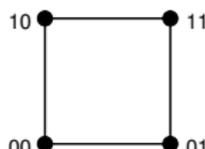
The **hypercube graph** Q_n has 2^n vertices, labeled by strings of n bits (0's and 1's), with two vertices adjacent if they agree in all but one bit.



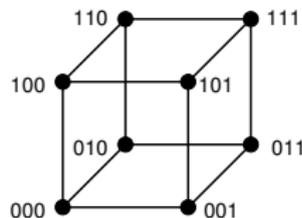
Q_0



Q_1



Q_2



Q_3

Theorem The eigenvalues of the Laplacian of Q_n are $0, 2, 4, \dots, 2n$, with $2k$ having multiplicity $\binom{n}{k}$. Therefore,

$$\tau(Q_n) = 2^{2^n - n - 1} \prod_{k=2}^n k \binom{n}{k}.$$

Threshold Graphs

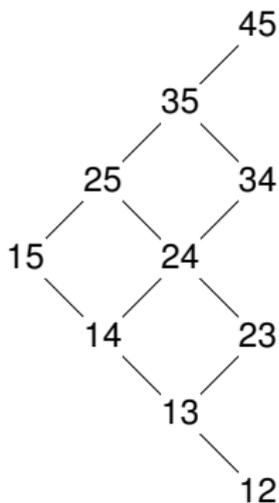
A graph G with vertex set $\{1, 2, \dots, n\}$ is a **threshold graph** if, whenever ab is an edge, so is $a'b'$ for all $a' \leq a$ and $b' \leq b$.

Equivalently, the edges of G form an order ideal under componentwise order.

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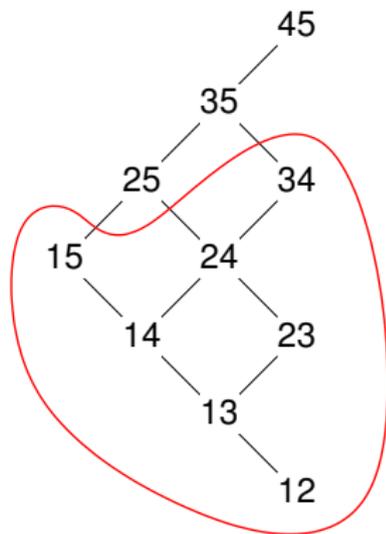
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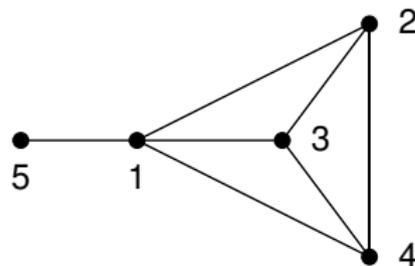
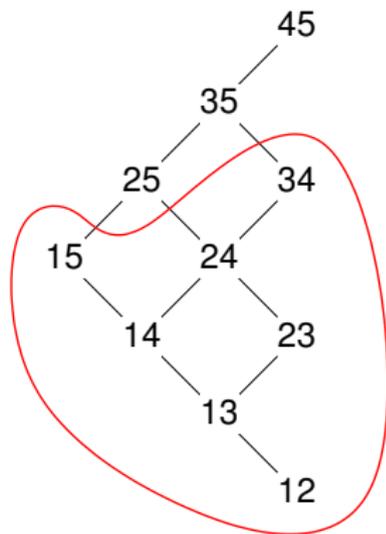
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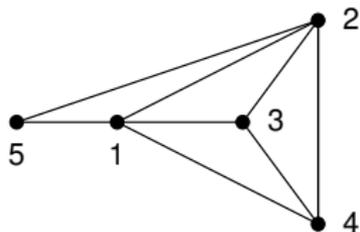
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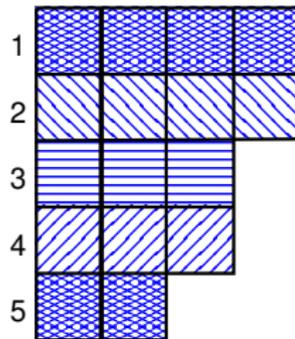
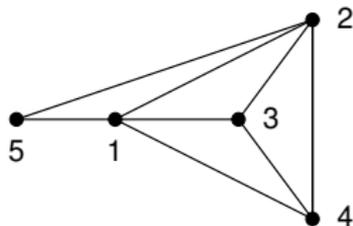
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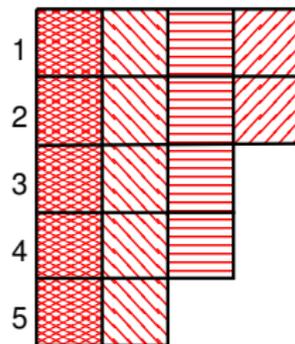
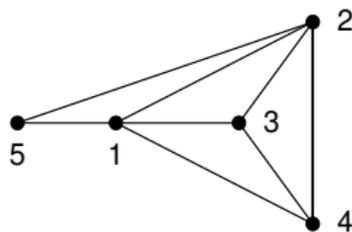


Vertex degrees: 4, 4, 3, 3, 2

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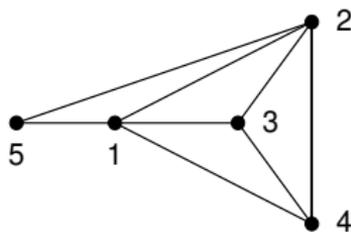


Laplacian eigenvalues: 5, 5, 4, 2, 0

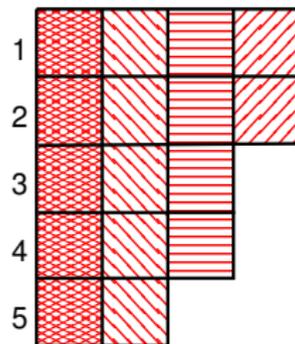
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Corollary $\tau(G) = \lambda'_2 \lambda'_3 \cdots \lambda'_{n-1}$.



$$\tau = 5 \times 4 \times 2 = 40$$



Laplacian eigenvalues: 5, 5, 4, 2, 0

Theorem [Cayley–Prüfer]

$$\sum_{T \in \mathcal{T}(K_n)} x_1^{\deg_T(1)} \cdots x_n^{\deg_T(n)} = x_1 \cdots x_n (x_1 + \cdots + x_n)^{n-2}$$

- ▶ Setting $x_i = 1$ for all i recovers $\tau(K_n) = n^{n-2}$
- ▶ Can be proved either bijectively (*Prüfer code*) or by a souped-up version of the Matrix-Tree Theorem
- ▶ Other weighted tree counting formulas:
 - ▶ *Via bijections*: Fiedler-Sedláček (complete bipartite graphs), Knuth, Kelmans, Remmel-Williamson, etc.
 - ▶ *Via MTT*: JLM–Reiner (threshold graphs, hypercubes)

Weighted Tree Counts for Threshold Graphs

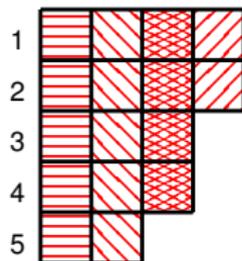
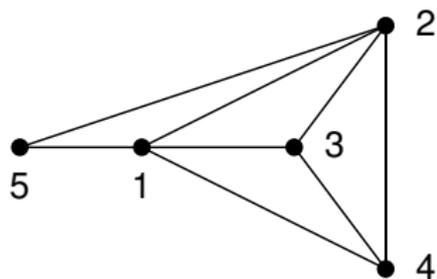
Theorem [JLM–Reiner 2005] Let G be a threshold graph on vertices $[n]$ with degree sequence λ . Weight each edge $e = ij$ with $i < j$ by $x_i y_j$. Then the **bidegree generating function** is

$$\sum_{T \in \mathcal{T}(G)} \prod_{e: i < j} x_i y_j = x_1 y_n \prod_{r=2}^{n-1} \left(\sum_{i=1}^{\lambda'_r} x_{\min(i,r)} y_{\max(i,r)} \right)$$

and therefore (setting $y_i = x_i$) the **degree generating function** is

$$\sum_{T \in \mathcal{T}(G)} \prod_{i=1}^n x_i^{\deg(i)} = x_1 \cdots x_n \prod_{r=2}^{n-1} \left(\sum_{i=1}^{\lambda'_r} x_i \right)$$

Weighted Tree Counts for Threshold Graphs



Bidegree generating function:

$$x_1 y_5 (x_1 y_2 + x_2 y_2 + x_2 y_3 + x_2 y_4 + x_2 y_5) \\ \times (x_1 y_3 + x_2 y_3 + x_3 y_3 + x_3 y_4)(x_1 y_4 + x_2 y_4)$$

Degree generating function:

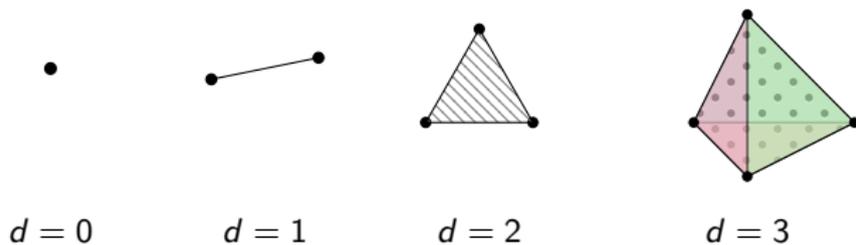
$$x_1 x_2 x_3 x_4 x_5 (x_1 + x_2 + x_3 + x_4 + x_5)(x_1 + x_2 + x_3 + x_4)(x_1 + x_2)$$

Simplicial Complexes

A **d -simplex** is the convex hull of $d + 1$ general points in \mathbb{R}^{d+1} .

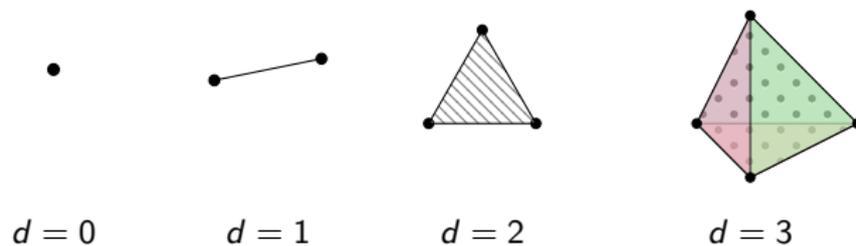
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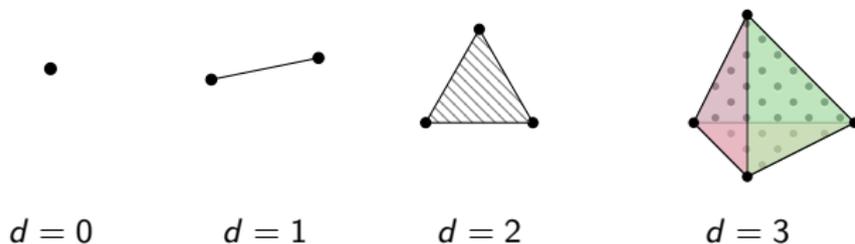
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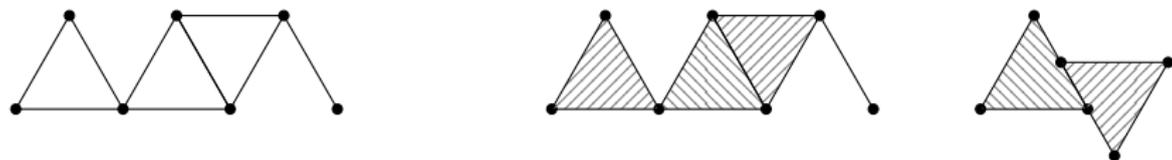
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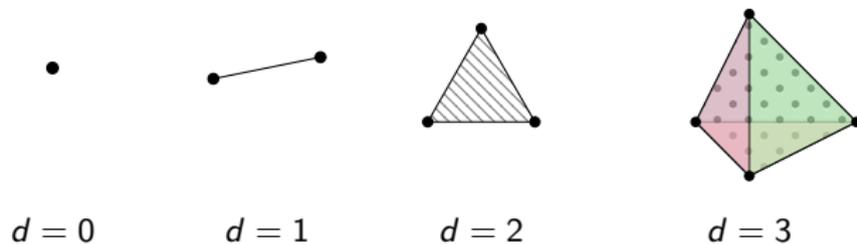


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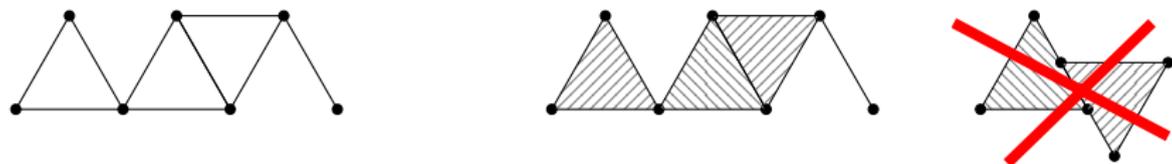


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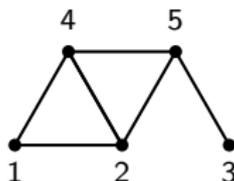


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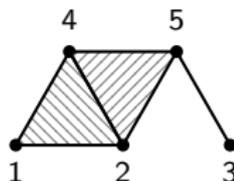


Simplicial Complexes

Combinatorially, a simplicial complex is a **set family** $\Delta \subseteq 2^{\{1,2,\dots,n\}}$ such that if $\sigma \in \Delta$ and $\sigma' \subseteq \sigma$, then $\sigma' \in \Delta$.



$$\Delta_1 = \langle 12, 14, 24, 25, 35 \rangle$$



$$\Delta_2 = \langle 124, 245, 35 \rangle$$

- ▶ **faces** or **simplices**: elements of Δ
- ▶ **dimension**: $\dim \sigma = |\sigma| - 1$
- ▶ **facet**: a maximal face
- ▶ **pure** complex: all facets have equal dimension

Simplicial Spanning Trees

Definition Let Δ^D be a simplicial complex of dimension d .

A subcomplex $\Upsilon \subseteq \Delta$ is a **simplicial spanning tree** (SST) if:

1. Υ contains all simplices of Δ of dimension $< d$.
2. Υ is “acyclic” and “connected”.
 - ▶ *Technically:* $\tilde{H}_d(\Upsilon; \mathbb{Q}) = \tilde{H}_{d-1}(\Upsilon; \mathbb{Q}) = 0$.
 - ▶ *Intuitively:* Υ has no “bubbles” whose boundary is an orientable d - or $(d - 1)$ -manifold.

As before, we'll write $\mathcal{T}(\Delta)$ for the set of SSTs of Δ .

Examples of SSTs

- ▶ $\dim \Delta = 1$: $\mathcal{T}(\Delta) =$ graph-theoretic spanning trees

Examples of SSTs

- ▶ $\dim \Delta = 1$: $\mathcal{T}(\Delta) =$ graph-theoretic spanning trees
- ▶ $\dim \Delta = 0$: $\mathcal{T}(\Delta) =$ vertices of Δ

Examples of SSTs

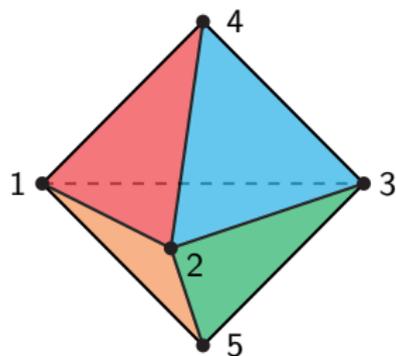
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- ▶ $\dim \Delta = 0$: $\mathcal{T}(\Delta) =$ vertices of Δ
- ▶ If Δ is **contractible**: it has only one SST, namely itself.
 - ▶ Contractible complexes \approx acyclic graphs
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 - ▶ Some noncontractible complexes also qualify, notably \mathbb{RP}^2
- ▶ If Δ is a **simplicial sphere**: SSTs are $\Delta \setminus \{\sigma\}$, where $\sigma \in \Delta$ is any facet (maximal face)
 - ▶ Simplicial spheres are analogous to cycle graphs

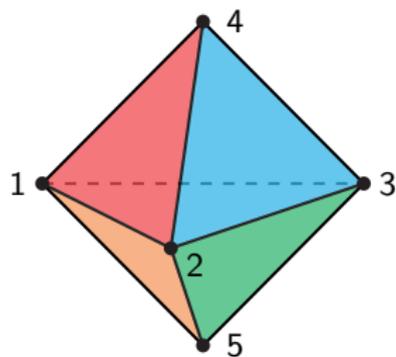
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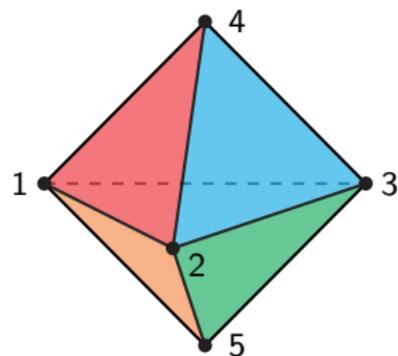
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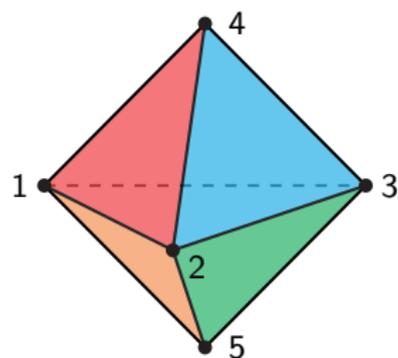


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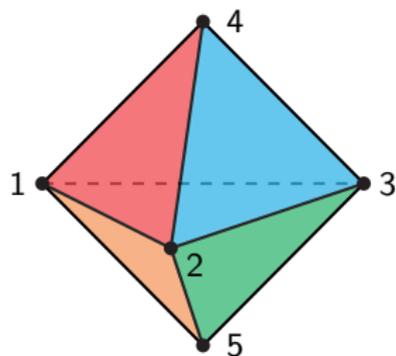


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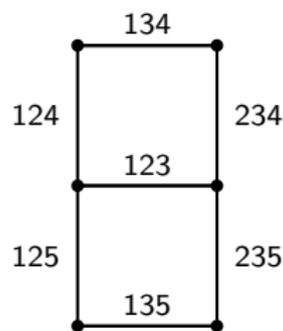
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Simplicial Boundary Maps and Homology

Let Δ be a simplicial complex on vertices $[n]$.
Write Δ_k for the set of k -dimensional faces.

The k^{th} **simplicial boundary matrix** of Δ is

$$\partial_k = \partial_k(\Delta) = [d_{\rho,\sigma}]_{\rho \in \Delta_{k-1}, \sigma \in \Delta_k}$$

where

$$d_{\rho,\sigma} = \begin{cases} (-1)^j & \text{if } \sigma = \{v_0 < v_1 < \dots < v_k\} \text{ and } \rho = \sigma \setminus v_j \\ 0 & \text{if } \rho \not\subseteq \sigma \end{cases}$$

Note: ∂_1 is the signed incidence matrix of the 1-skeleton of Δ .

Fact: $\ker \partial_k \supseteq \text{im } \partial_{k+1}$ for all k . (Check it!)

Simplicial Boundary Maps and Homology

Fact: $\ker \partial_k \supseteq \text{im } \partial_{k+1}$ for all k . In other words, the sequence

$$\cdots \rightarrow R\Delta_{k+1} \xrightarrow{\partial_{k+1}} R\Delta_k \xrightarrow{\partial_k} R\Delta_{k-1} \rightarrow \cdots$$

is a **chain complex** for any ring R . (Default in this talk: $R = \mathbb{Z}$.)

The **homology groups** of Δ are

$$\tilde{H}_k(\Delta; R) = \ker \partial_k / \text{im } \partial_{k+1}.$$

These are topological invariants of Δ .

- ▶ $\tilde{H}_0(\Delta) = 0 \iff \Delta$ is connected
- ▶ $\tilde{H}_1(\Delta) = 0 \iff \Delta$ is simply connected (essentially)
- ▶ If Δ is contractible then $\tilde{H}_k(\Delta) = 0$ for all k

Simplicial Laplacians

The k^{th} **(updown) Laplacian matrix** of a simplicial complex Δ is

$$L_{k-1}^{\text{ud}}(\Delta) = \partial_k \partial_k^T.$$

- ▶ $L_0^{\text{ud}}(\Delta)$ is the usual graph Laplacian.
- ▶ $L_{k-1}^{\text{ud}}(\Delta)$ is a square matrix with entries

$$\ell_{\rho, \pi} = \begin{cases} \#\{\sigma \in \Delta_k \mid \sigma \supseteq \rho\} & \text{if } \rho = \pi, \\ \pm 1 & \text{if } \rho, \pi \text{ lie in a common } k\text{-face,} \\ 0 & \text{otherwise} \end{cases}$$

for $\rho, \pi \in \Delta_{k-1}$.

The Simplicial Matrix-Tree Theorem (Roughly)

Simplicial Matrix-Tree Theorem

(Bolker, Kalai, Adin, Duval–Klivans–JLM, ...)

Let Δ^d be a simplicial complex.

Form a **reduced Laplacian** $L_T(\Delta)$ from $L(\Delta)$ by deleting the rows and columns corresponding to a $(d - 1)$ -dimensional SST $T \subseteq \Delta$.

Then the **“number”** of spanning trees of Δ is $\det L_T$, divided by a **correction factor** given by T .

The Simplicial Matrix-Tree Theorem (Precisely)

The **torsion** of a spanning tree $\Upsilon \in \mathcal{T}(\Delta)$ is

$$|\tilde{H}_{d-1}(\Upsilon; \mathbb{Z})| = |\ker \partial_{d-1}(\Upsilon) / \text{im } \partial_d(\Upsilon)|$$

(which must be finite).

- ▶ This number is 1 if $\dim \Delta \leq 1$.
- ▶ Torsion \approx non-orientability: e.g., $\tilde{H}_1(\mathbb{RP}^2) = \mathbb{Z}/2\mathbb{Z}$.

Simplicial Matrix-Tree Theorem

$$\tau(\Delta) \stackrel{\text{def}}{=} \sum_{\Upsilon \in \mathcal{T}(\Delta)} |\tilde{H}_{d-1}(\Upsilon; \mathbb{Z})|^2 = \frac{|\tilde{H}_{d-2}(\Delta)|}{|\tilde{H}_{d-2}(T)|} \det \hat{L}_T$$

If $d = 1$ then all summands are 1.

In many natural cases, the correction factor is trivial.

Kalai's Theorem

Simplicial generalization of the complete graph:

$$K_{n,d} = \{F \subseteq \{1, \dots, n\} \mid \dim F \leq d\}$$

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Theorem [Kalai 1983]

$$\tau(K_{n,d}) = n \binom{n-2}{d}.$$

More generally,

$$\sum_{\gamma \in \mathcal{T}(K)} |\tilde{H}_{d-1}(\gamma; \mathbb{Z})|^2 \prod_{i=1}^n x_i^{\deg \gamma(i)} = (x_1 \cdots x_n)^{\binom{n-2}{d-1}} (x_1 + \cdots + x_n)^{\binom{n-2}{d}}.$$

Kalai's Theorem

- ▶ Kalai's theorem reduces to $\tau(K_n) = n^{n-2}$ when $d = 1$, and the weighted version reduces to Cayley-Prüfer.
- ▶ Bolker (1976): Observed that $n \binom{n-2}{d}$ is an exact count of trees for small n, d , but fails for $n = 6, d = 2$.
 - ▶ The problem is torsion — \mathbb{RP}^2 requires six vertices to triangulate
- ▶ Adin (1992): Analogous formula for **complete colorful complexes**, generalizing $\tau(K_{n,m}) = n^{m-1} m^{n-1}$

Shifted Simplicial Complexes

A simplicial complex Δ with vertex set $\{1, 2, \dots, n\}$ is **shifted** if whenever $a_1 a_2 \cdots a_k \in \Delta$ and $b_i \leq a_i$ for all i , then $b_1 b_2 \cdots b_k \in \Delta$.

(So one-dimensional shifted complexes are just threshold graphs.)

Theorem [Duval–Reiner 2002]

Let $\lambda_i =$ number of max-dim faces containing i .

Then eigenvalues of $L(\Delta) =$ column lengths of λ .

(Generalization of Merris' Theorem)

Theorem [Duval–Klivans–JLM 2009]

Factorization of multidegree g.f. for spanning trees of a shifted complex. (Generalization of JLM–Reiner formula)

Further Directions

- ▶ Theory of SSTs and the Matrix-Tree Theorem generalize easily from simplicial complexes to **cell complexes**
 - ▶ Cubes and their skeletons [Duval–Klivans–JLM 2011], [Aalipour–Duval–Kook–Lee–JLM 2017⁺]
 - ▶ Cellular MTT discovered independently in contexts of probability [Lyons 2009] and mathematical physics [Catanzaro–Chernyak–Klein 2015]
- ▶ Simplicial/cell complexes that have **integer Laplacian eigenvalues** “should” have factorizable weighted tree g.f.’s
 - ▶ Matroid complexes; others?
- ▶ **Critical groups:**
 - ▶ Complex $\Delta \Rightarrow$ abelian group $K(\Delta)$ of size $\tau(\Delta)$
 - ▶ Cuts, flows, sandpile theory, “algebraic geometry on graphs”
 - ▶ Group structure very mysterious